US 20020066149A1

(19) **United States**

(12) **Patent Application Publication** (10) **Pub. No.: US 2002/0066149 A1**

Gerber et al. (43) **Pub. Date: Jun. 6, 2002**

(54) **RANDOM MOTION CLEANER**

(76) Inventors: **Douglas E. Gerber**, North Canton, OH (US); **Kevin L. Thomas**, North Canton, OH (US)

Correspondence Address:
A. Burgess Lowe
101 East Maple Street
North Canton, OH 44720 (US)

(21) Appl. No.: **09/727,724**

(22) Filed: **Dec. 1, 2000**

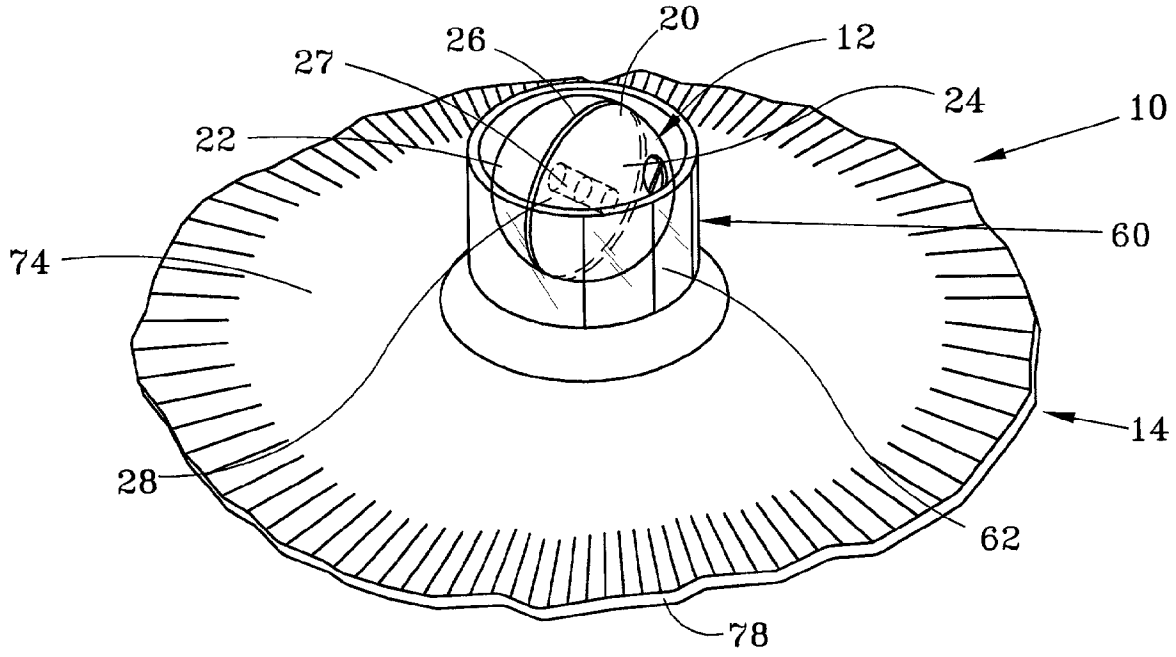
Publication Classification

(51) **Int. Cl.**[7] **A47L 11/10**

(52) **U.S. Cl.** **15/98**; 134/6

(57) **ABSTRACT**

A self-propelled bare floor cleaner is provided having a random motion generator which enhances the maneuverability of the bare floor cleaner. The random motion generator is rotatably attached to the frame of the cleaner and propels the cleaner across the floor in a random motion. This random motion facilitates cleaning of the floor by making the cleaner easier to manipulate. The random motion generator includes a hollow spherical shell. In the preferred embodiment, the hollow spherical shell houses a weighted motor assembly which is rotatably mounted on a center fixed axle which extends diametrically between the first and second hemispherical halves and is attached thereto. The weighted motor assembly is comprised of a motor housing and a power source, such as batteries or cells. A motor is housed within the motor housing and rotates the motor housing about the center fixed axle. The power source is mounted to one side of the motor housing to provide an unbalanced weight to the motor assembly relative to the fixed center. This unbalanced weight causes the random motion generator to roll across the floor in a random motion and, thus, the bare floor cleaner is also propelled across the floor in a random motion to facilitate cleaning of the floor.



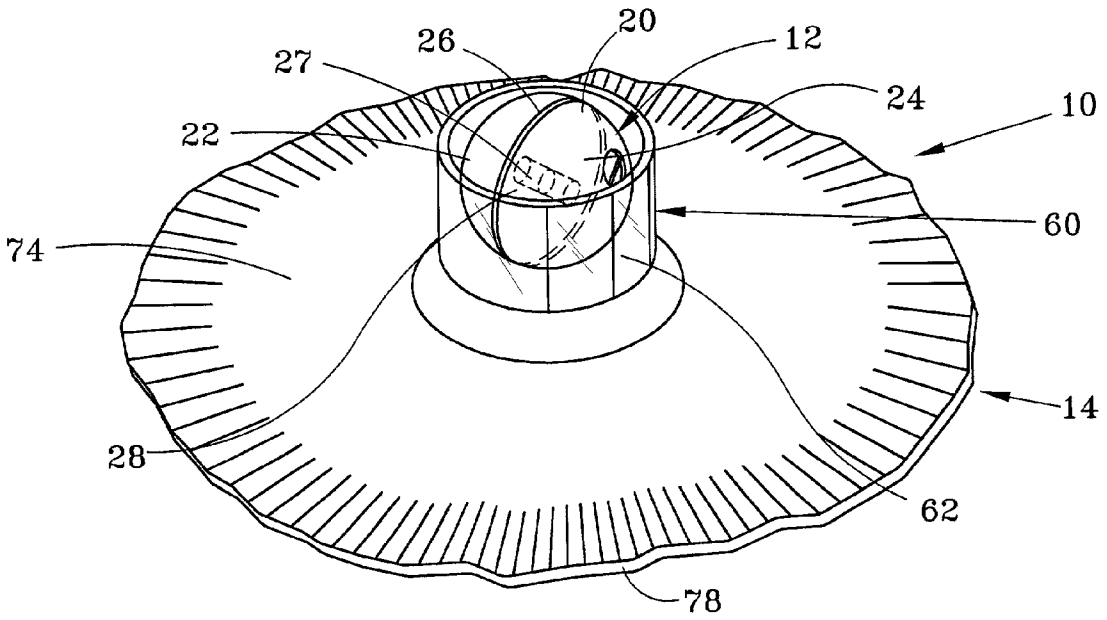

20
26
12
27
24
10
22
60
74
14
28
62
78

FIG-1

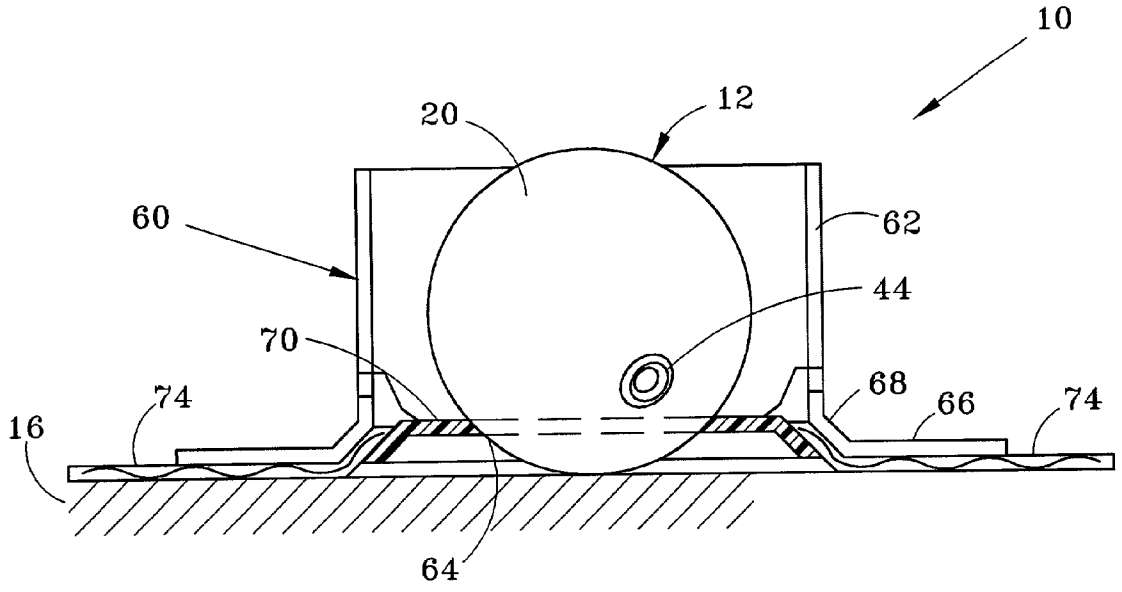

10
20
12
60
62
44
70
74
68
66
74
16
64

FIG-2

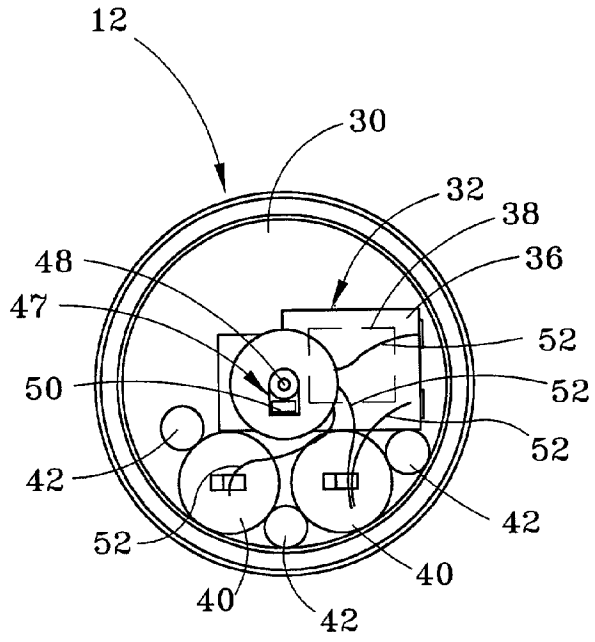

12
30
32
38
36
48
47
52
50
52
52
42
42
52
40
40
42

FIG-3

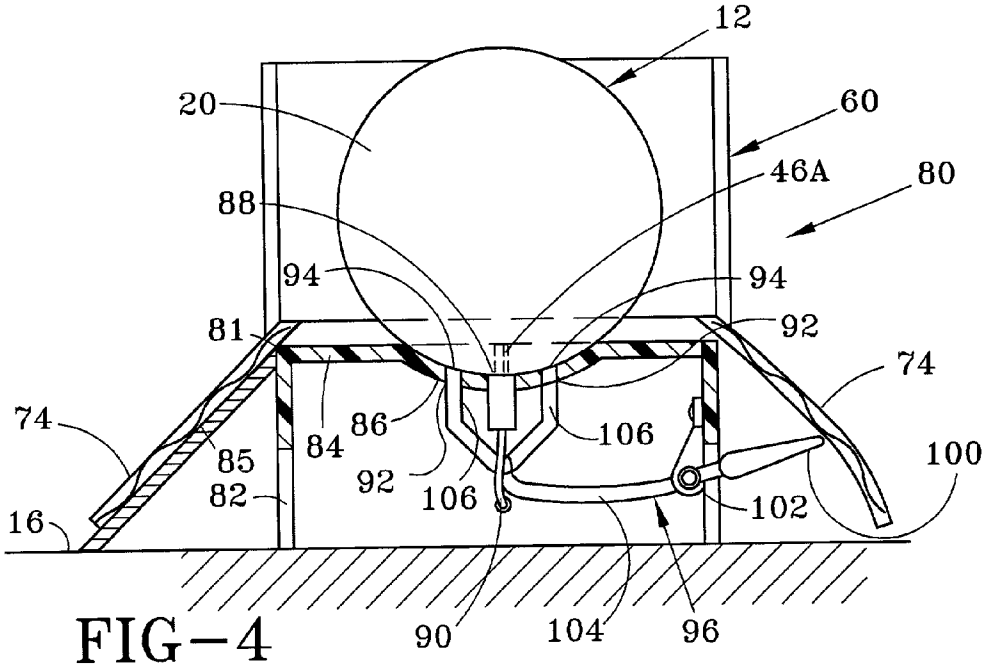

12
20
60
46A
80
88
94
94
81
92
74
74
86
84
106
85
92
106
82
102
100
16
90
104
96

FIG-4

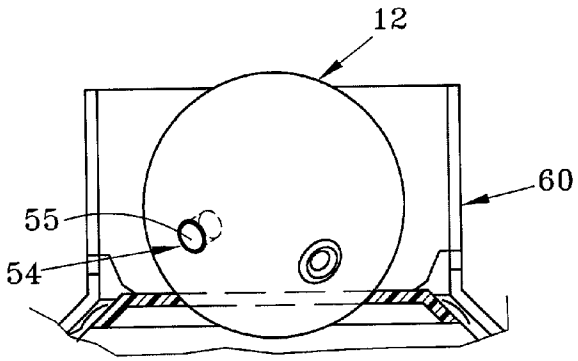


FIG-5

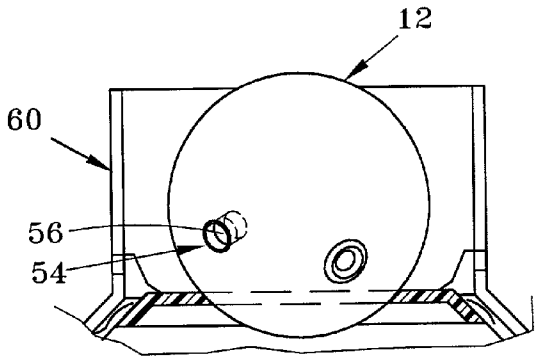


FIG-5A

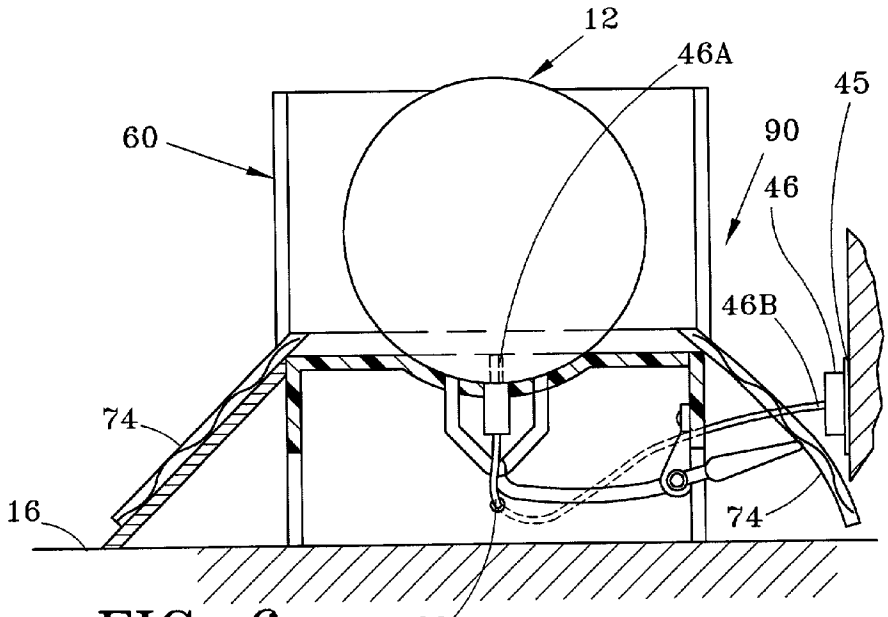


FIG-6

RANDOM MOTION CLEANER

BACKGROUND OF THE INVENTION

[0001] 1. Field of Invention

[0002] This invention pertains to bare floor cleaners. More specifically, this invention pertains to a self-propelled bare floor cleaner which utilizes a spherical random motion device to randomly propel a cleaning device about a bare floor for use in picking up dirt and debris therefrom.

[0003] 2. Description of Related Prior Art

[0004] It is known in the prior art to provide bare floor cleaners for use in removing dust and debris from hardwood floors, linoleum, tile and the like. Examples of such bare floor cleaners are dry mops, stick vacuum cleaners and upright vacuum cleaners. These cleaners have proven adequate for their intended purpose. However, they are known to be cumbersome and difficult to manipulate. Furthermore, these bare floor cleaners do not allow for easy cleaning of the floor surface under furniture without moving the furniture or significant bending or stooping.

[0005] It is also known in the prior art to provide self-propelled floor cleaners. These cleaners work well in buildings having wide, open or otherwise well-defined spaces. However, the cleaners are provided with a power cord, which is plugged into an AC receptacle, and the power cord tends to get caught or snagged on furniture and other household objects, thereby, making these cleaners unsuitable for home use.

[0006] Hart Enterprises, Inc. produces the Squiggle Ball™, comprising a hollow spherical ball formed of two spherical halves that are threaded together to form a hollow, spherical shell. Once activated, the Squiggle Ball™ randomly rolls along a provided surface. Further, the Squiggle Ball™ utilizes one AA type battery and has a finger actuated, combined push and rotate on/off power switch. The Squiggle Ball cannot be used as a cleaning device and its use is primarily for entertainment of pets and/or children.

[0007] In U.S. Pat. No. 4,306,329, a self-propelled cleaning device having an internal power source is disclosed. The cleaning device uses a battery power supply and, thus, the need for a power cord is eliminated. However, the movement of the device is limited to either rotation about its axis at a fixed stationary point or motion in a straight line. This limited motion makes use of the cleaner in a home environment difficult and cumbersome. The cleaner cannot be easily maneuvered around furniture and other household objects.

[0008] The present invention utilizes a novel method and apparatus for overcoming these problems. A random motion generator is provided which operatively attaches to a bare floor cleaner to facilitate maneuverability of the cleaner. The random motion generator propels the bare floor cleaner across floors in a random motion. This random motion enables the bare floor cleaner to easily maneuver around furniture and other household objects. Furthermore, this random motion prevents the bare floor cleaner from being caught in corners and other such confined spaces.

SUMMARY OF THE INVENTION

[0009] It is therefore an object of the present invention to provide an improved self-propelled bare floor cleaner which is capable of removing dust and debris from a bare floor surface.

[0010] It is a further objective of this invention to provide an improved self-propelled bare floor cleaner which requires minimal manual manipulation thereof.

[0011] It is still a further objective to provide an improved self-propelled bare floor cleaner capable of cleaning beneath furniture without moving the same.

[0012] It is still a further objective to provide an improved self-propelled bare floor cleaner which is easily maneuvered around furniture and other household objects.

[0013] These and other objectives of the present invention are achieved by one embodiment of the present invention disclosed herein wherein there is provided a self-propelled bare floor cleaner having a random motion generator for randomly propelling the cleaner across a floor. The random motion generator includes a hollow spherical shell formed from first and second hemispherical halves. The hollow spherical shell houses a weighted motor assembly which is rotatably mounted on a center fixed axle which extends diametrically between the first and second hemispherical halves and is attached thereto. The weighted motor assembly is comprised of a motor housing and a power source, such as batteries or cells. A motor is housed within the motor housing and rotates the motor housing about the center fixed axle. The power source is mounted to one side of the motor housing to provide an unbalanced weight to the motor assembly relative to the fixed center. This unbalanced weight causes the random motion generator to roll across the floor in a random motion and, thus, the bare floor cleaner is also propelled across the floor in a random motion to facilitate cleaning thereof.

BRIEF DESCRIPTION OF THE DRAWINGS

[0014] A preferred embodiment of the present invention will now be described, by way of example, with reference to the accompanying drawings, of which:

[0015] **FIG. 1** is a perspective view of a self-propelled bare floor cleaner having a random motion generator according to the present invention;

[0016] **FIG. 2** is a side-sectional view of the self-propelled bare floor cleaner having a random motion generator;

[0017] **FIG. 3** is a sectional view of the random motion generator;

[0018] **FIG. 4** is a side sectional view of a charging stand for the random motion generator;

[0019] **FIG. 5** is a side sectional view of the present invention showing a power switch on the random motion generator in the activated position;

[0020] **FIG. 5A** is a side sectional view of the present invention showing a power switch on the random motion generator in the deactivated position; and

[0021] **FIG. 6** is a side sectional view of the present invention showing the AC to DC adapter and the AC power receptacle.

DETAILED DESCRIPTION OF THE INVENTION

[0022] A self-propelled bare floor cleaner **10** having a random motion generator **12** according to a preferred

embodiment of the present invention is illustrated by way of example in **FIGS. 1 and 2**. The floor cleaner **10** is comprised of a cleaning assembly **14** which is randomly propelled over bare floors **16** by the random motion generator **12**.

[**0023**] Continuing to view **FIGS. 1 and 2**, the cleaning assembly **14** includes a frame **60**, a means for securing the random motion generator **12** to the frame **60** and a cleaning device, which in the preferred embodiment is dust cloth **74**. The frame **60** comprises a cylindrical wall **62** having an open first end **64** and an angled wall section **68** attached thereto and extending downward and outward therefrom. A peripheral lip **66** attaches to the angled wall section **68** and extends outward and parallel to the floor **16**. The peripheral lip **66** may comprise patches of Teflon®, felt or other low friction material on its lower surface to facilitate sliding of the frame **60** over the underlying surface **16**. Further, the open first end **64** of the cylindrical wall **62** receives the random motion generator **12**, and the diameter of the open first end **64** is slightly larger than the diameter of the random motion generator **12**, which allows the random motion generator **12** to be positioned within the cylindrical wall **62**. The random motion generator **12** is rotatably attached to the frame **60** and is positioned in such a manner as to allow the random motion generator **12** to contact the floor **16** and roll thereon.

[**0024**] Since the diameter of the open first end **64** is larger than the diameter of the random motion generator **12**, a securing means is used to secure the random motion generator **12** to the frame **60**. In the preferred embodiment, the securing means is comprised of an inner annular lip **70**, best seen in **FIG. 2**. The inner annular lip **70** extends inwardly from the first end of the cylindrical wall **62** and is spaced slightly above the floor **16**. Further, the surface of the lip **70** contacting the random motion generator **12** may comprise dimples to decrease friction between the random motion generator **12** and the frame **60**. However, any securing means which secures the random motion generator **12** to the frame **60** and allows the random motion generator **12** to roll randomly across the floor **16** is within the scope of this invention. Also, a cover (not shown) may be provided for enclosing the top of the cylindrical frame **60** to further secure the random motion generator **12** therein and to enhance the appearance of the self-propelled bare floor cleaner **10**.

[**0025**] The dust cloth **74** has a frayed peripheral edge **78** for picking up dust and debris from the floor **16**. Additionally, the dust cloth **74** may be sprayed with a cleaning solution to enhance the collection of dust and debris. In the preferred embodiment, the dust cloth is removably attached to the frame **60** so that the dust cloth **74** can be removed from the frame **60** and cleaned. In **FIG. 2**, the dust cloth **74** is removably attached to the bottom surface of the peripheral lip **66** and the angled wall section **68**. However, the dust cloth **74** may be secured to the frame **60** in any manner which allows the dust cloth **74** to adequately contact the floor **16**. Similarly, any securing means, such as, hook and loop type fasteners, adhesives, or double sided tapes, may be used to secure the dust cloth **74** to the frame **60**.

[**0026**] Turning now to **FIGS. 5 and 5A**, the random motion generator **12** may also include a power switch **54** having first and second positions **55**, **56** for selectively activating a weighted motor assembly **32**, (shown in **FIG. 3**), as will be explained in further detail below. The power switch **54** may attach to the random motion generator **12** and operatively connect to the weighted motor assembly **32** (shown in **FIG. 3**). The weighted motor assembly **32** (shown in **FIG. 3**) is activated by moving the power switch to its first position **55**, as seen in **FIG. 5**. Similarly, the weighted motor assembly **32** (shown in **FIG. 3**) is deactivated by moving the power switch to its second position **56**, as shown in **FIG. 5A**. No matter what type of power switch **54** is utilized, its activation or first position **55** should not inhibit the random rolling motion of the random motion generator **12** on the underlying surface **16**.

[**0027**] With continuing reference to **FIGS. 1 and 2**, the random motion generator **12** is illustrated. The random motion generator **12** includes a hollow spherical shell **20** which in the preferred embodiment is formed from first and second hemispherical halves **22** and **24**. The hemispherical halves **22** and **24** have mated threads for removably securing the hemispherical halves **22** and **24** to each other. However, any means, such as snaps or screws, which removably secures the hemispherical halves **22** and **24** to each other may be used.

[**0028**] In the preferred embodiment, a rubber ring **26** is mounted between the hemispherical halves **22** and **24** and extends outwardly from an outer surface **28** of the spherical shell **20**, as shown in **FIG. 1**. The rubber ring **26** causes the spherical shell **20** to incline slightly to one side or the other and to roll along a slightly curved path. This enhances the random rolling of the random motion generator **12**, as will be explained in further detail below.

[**0029**] With reference to **FIG. 3**, in the preferred embodiment spherical shell **20** has a hollow interior **30** for housing a weighted motor assembly **32**. The weighted motor assembly **32** is rotatably mounted on a center fixed axle **27** which extends diametrically across opposing sides of the sphere between the hemispherical halves **22** and **24** of the random motion generator **12** and is attached thereto. The weighted motor assembly **32** is comprised of a motor housing **36** and a power means, such as, batteries **40**. A motor **38** is housed within the motor housing **36** and rotates the motor housing **36** about the center fixed axle **27**. The batteries **40** are attached to one side of the motor housing **36** to provide an unbalanced weight to the motor assembly **32** relative to the center fixed axle **27** which causes the random motion generator **12** to roll across the floor in a random motion. A plurality of wires **52** extends between the motor and the batteries **40** to provide the necessary electrical connections therebetween.

[**0030**] In the preferred embodiment, weights **42** are attached to the batteries **40** and/or the motor housing **36** on the same side of the motor housing **36** as the batteries **40**. This increases the unbalanced weight of the motor assembly **32** relative to the center fixed axle **27** which enhances the random rolling of the random motion generator **12**.

[**0031**] In the preferred embodiment, rechargeable batteries **40** are used to power the motor **38**. Rechargeable batteries **40** are preferred because they can be recharged without having to disassemble the random motion generator **12**, which must be disassembled to replace the non-rechargeable batteries **40**. Disassembly of the random motion generator **12** is time consuming and can cause damage to the random motion generator **12**.

[**0032**] With reference to **FIGS. 4 and 6**, a charging stand **80** for recharging the rechargeable batteries **40** is illustrated.

The charging stand **80** is comprised of a cylindrical wall **82** having a first end, a support platform **84**, and an AC to DC power adapter **46** having first and second ends **46***a*, **46***b*. The support platform **84** is mounted to the first end **81** of the cylindrical wall **82**. The support platform **84** includes a circular indentation **86** for receiving the random motion generator **12** and an opening **88** positioned within the circular indentation **86** for receiving the first end **46***a* of the power adapter **46**. Viewing **FIG. 6**, the second end **46***b* of the power adapter **46** is connected to a power cord **90** which can be plugged into an AC power receptacle **45** to recharge the batteries **40**.

[**0033**] The random motion generator **12** has a receiving mechanism **47** for receiving the DC charge and transmitting it to the batteries **40**, as shown in **FIG. 3**. The receiving mechanism **47** includes a receptacle **48** for receiving the first end **46***a* of the power adapter **46** and a switch **50**. The receptacle **48** is mounted on the motor assembly **32** and positioned within an opening **44** located on either the first or the second hemispherical half **22** and **24** of the random motion generator **12**. During periods of non-use, the random motion generator **12** is recharged by plugging the first end **46***a* of the power adapter **46** into the receptacle **48**, which has a complimentary shape. When the first end **46***a* of the power adapter **46** is plugged into the receptacle, the switch, which is positioned adjacent to the receptacle **48**, turns the motor assembly **32** off to enable recharging of the batteries **40**. A plurality of wires **52** extends between the motor **38**, batteries **40**, receptacle **48** and switch **50** to provide the necessary electrical connectors therebetween.

[**0034**] In the preferred embodiment, the charging stand **80** includes an ejection assembly **96**, as shown in **FIG. 4**. During periods of use, the ejection assembly **96** is used to remove the random motion generator **12** from the charging stand **80**. The ejection assembly **96** is comprised of an ejection arm **106**, a linkage arm **104** having first and second ends, a support **102** and a foot pedal **100**. The ejection arm **106** extends through two apertures **92** in the support platform **84**. The apertures **92** are positioned diametrically opposite one another with the opening **88** formed therebetween. The ejection arm **106** is attached to the first end of the linkage arm **104** and the second end of the linkage arm **104** is attached to the support **102**. The foot pedal **100** is pivotally mounted to the support **102**. When the foot pedal **100** is depressed, the ejection arm **106** is projected through the apertures **92** in the support platform **84** and contacts the random motion generator **12**. The ejection arm **106** exerts an upward force on the random motion generator **12** which results in the random motion generator **12** being ejected from the charging stand **80**. When the random motion generator **12** is ejected from the charging stand **80**, the first end **46***a* of the AC to DC power adapter **46** is removed from the receptacle **48** which activates the switch **50** and turns the random motion generator **12** on to facilitate use of the bare floor cleaner **10**. A ramp **85** may be operatively attached to the cylindrical wall **82** and/or the support platform **84** to facilitate removal of the random motion generator **12** from the charging stand **80** by allowing the random motion generator **12** to roll down the ramp **85** to the floor **16** without damage.

[**0035**] In **FIG. 4**, the random motion generator **12** is shown without the cleaning assembly **14**. However, the cleaning assembly **14** may be attached to the random motion generator **12** during charging of the random motion generator **12** on the charging stand **80**.

[**0036**] A method of using the self-propelled bare floor cleaner **10** according to the present invention includes the steps of activating the weighted motor assembly **32** either by depressing the foot pedal **100** to eject the random motion generator **12** from the charging stand **80**, thereby, causing the switch **50** to activate the weighted motor assembly **32** or by moving the power switch **54** to the first position **55** to activate the weighted motor assembly **32**, contacting the spherical shell **20** with the floor **16** and randomly propelling the bare floor cleaner **10** across the floor **16** to pick up dirt and debris therefrom.

[**0037**] The present invention has been described above using a preferred embodiment by way of example only. Obvious modifications within the scope of the present invention will become apparent to one of ordinary skill upon reading the above description and viewing the appended drawings. The present invention described above and as claimed in the appended claims is intended to include all such obvious modifications within the scope of the present invention.

What is claimed is:

1. A self-propelled bare floor cleaner, comprising:

a cleaning assembly; and

a random motion generator operatively connected to said dusting assembly, said cleaning assembly comprising:

a frame having a wall;

a securing mechanism for securing the random motion generator within the frame; and

a cleaning device attaching to the frame.

2. The self propelled bare floor cleaner of claim 1, wherein said random motion generator includes:

a hollow substantially spherical shell rotatably attached to the frame; and

a weighted motor assembly having a motor for rotating the random motion generator and rotatably attached to a center fixed axle, the center fixed axle extending diametrically across opposing sides of said spherical shell.

3. The self-propelled bare floor cleaner of claim 2, wherein said weighted motor assembly includes a motor housing for housing the motor and a power source being operatively mounted to one side of the motor housing to provide an unbalanced weight to the weighted motor assembly.

4. The self-propelled bare floor cleaner of claim 3, wherein at least one weight is operatively mounted to the same side of the weighted motor assembly as the power source.

5. The self-propelled bare floor cleaner of claim 3, wherein the power source is at least one battery.

6. The self-propelled bare floor cleaner of claim 5, wherein the at least one battery is rechargeable.

7. The self-propelled bare floor cleaner of claim 6, wherein the random motion generator includes a receiving mechanism for recharging the rechargeable battery.

8. The self-propelled bare floor cleaner of claim 7, wherein the receiving mechanism includes:

a receptacle operatively connected to the weighted motor assembly and fixedly positioned within a first opening of the random motion generator; and,

a switch operatively connected to the receptacle and the weighted motor assembly,

wherein when an AC to DC power adapter contacts the receptacle, the switch turns the weighted motor assembly off to facilitate charging of the at least one battery, and when the AC to DC power adapter is removed from the receptacle, the switch turns the weighted motor assembly on to facilitate use of the bare floor cleaner.

9. The self-propelled bare floor cleaner of claim 1, wherein the frame includes:

a cylindrical wall having a first end, the first end of the cylindrical wall forming a first cylindrical wall opening having a diameter larger than the diameter of the random motion generator, the first cylindrical wall opening receiving the random motion generator;

an angled wall section attached to the first end of the cylindrical wall and extending outwardly therefrom; and,

a peripheral lip attached to the angled wall.

10. The self-propelled bare floor cleaner of claim 1, wherein the securing mechanism for securing the random motion generator within the frame includes an inner lip, the inner lip operatively attaching to the first end of the cylindrical wall of the frame.

11. The self-propelled bare floor cleaner of claim 2, further comprising:

a power switch having first and second positions, the power switch operatively connected to the weighted motor assembly, wherein when the power switch is in the first position, the weighted motor assembly is activated and when the power switch is in the second position, the weighted motor assembly is deactivated.

12. The self-propelled bare floor cleaner of claim 2, wherein the random motion generator includes a rubber ring operatively mounted on the perimeter of said spherical shell.

13. A charging stand for charging a self-propelled bare floor cleaner having a random motion generator, comprising:

a cylindrical wall having a first end;

a support platform operatively attached to the first end of the cylindrical wall, the support platform including an indentation for receiving the random motion generator, the indentation having a first opening defined therein; and

a power source communicating with a power receptacle to recharge the random motion generator.

14. The charging stand of claim 13, wherein the power source is an AC to DC power adapter having first and second ends, the first end of the AC to DC power adapter being received by the first opening in the indentation of the support platform and the second end of the AC to DC power adapter connecting to a power cord for communication with an AC power receptacle to recharge the random motion generator.

15. The charging stand of claim 13, further comprising a ramp for facilitating removal of the random motion generator.

16. The charging stand of claim 13, further comprising an ejection assembly for ejecting the random motion generator.

17. The charging stand of claim 16, wherein the ejection assembly includes:

an ejection arm, said ejection arm being received by at least one aperture defined in the support platform;

a linkage arm having first and second ends, said first end of the linkage arm being operatively connected to the ejection arm;

a support operatively connected to the second end of the linkage arm; and,

a foot pedal pivotally connected to the support, wherein when the foot pedal is depressed the ejection arm is projected through the aperture in the support platform and contacts the random motion generator positioned in the support platform and ejects the random motion generator.

18. The charging stand of claim 17, further comprising a second aperture defined in the support platform and being diametrically opposed to the at least one aperture defined in the support platform.

19. A method of cleaning a bare floor comprising the steps of:

providing a self-propelled bare floor cleaner having a cleaning device, a frame attached to the cleaning device, and a random motion generator rotatably mounted to the frame;

activating the power source to the random motion generator;

contacting the floor with the random motion generator; and,

propelling the bare floor cleaner across the floor in a random motion to cause the cleaning device to clean the bare floor.

20. The self propelled bare floor cleaner of claim 2, wherein said hollow substantially spherical shell includes first and second hemispherical halves.

21. The self propelled bare floor cleaner of claim 1, wherein said cleaning device is a dust cloth.

* * * * *