



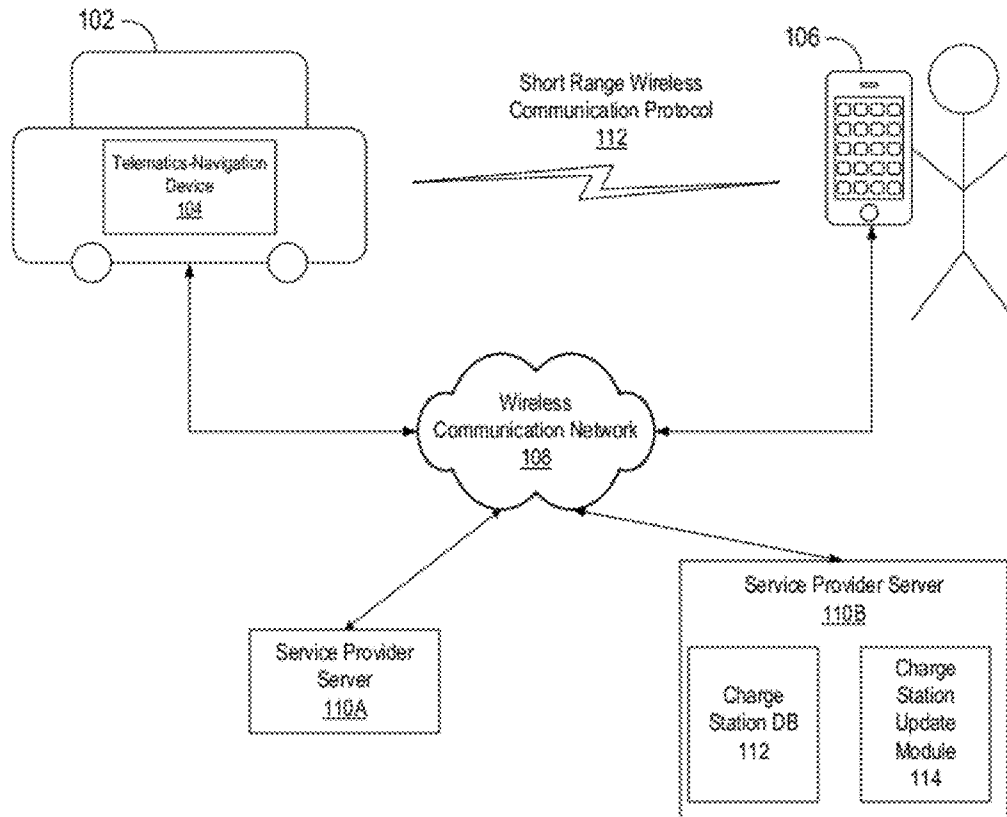
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Uyeki(10) **Pub. No.: US 2012/0123670 A1**(43) **Pub. Date: May 17, 2012**(54) **SYSTEM AND METHOD FOR UPDATING
CHARGE STATION INFORMATION****Publication Classification**(75) Inventor: **Robert Uyeki**, Torrance, CA (US)(73) Assignee: **HONDA MOTOR CO., LTD.**,
Tokyo (JP)(21) Appl. No.: **12/973,626**(22) Filed: **Dec. 20, 2010****Related U.S. Application Data**(60) Provisional application No. 61/414,396, filed on Nov.
16, 2010.(51) **Int. Cl.****G06F 17/00** (2006.01)**G06F 17/30** (2006.01)(52) **U.S. Cl. 701/300; 707/802; 707/E17.005**

(57)

ABSTRACT

A system for updating a charge station database including information about charge station location and/or characteristic by determining and verifying charge station location and characteristics after a vehicle connects to a charging station. The vehicle determines (probes) the charge station location based upon the location of the vehicle while connected to the charging station. This location information is transmitted by the vehicle to a central database.

100

100

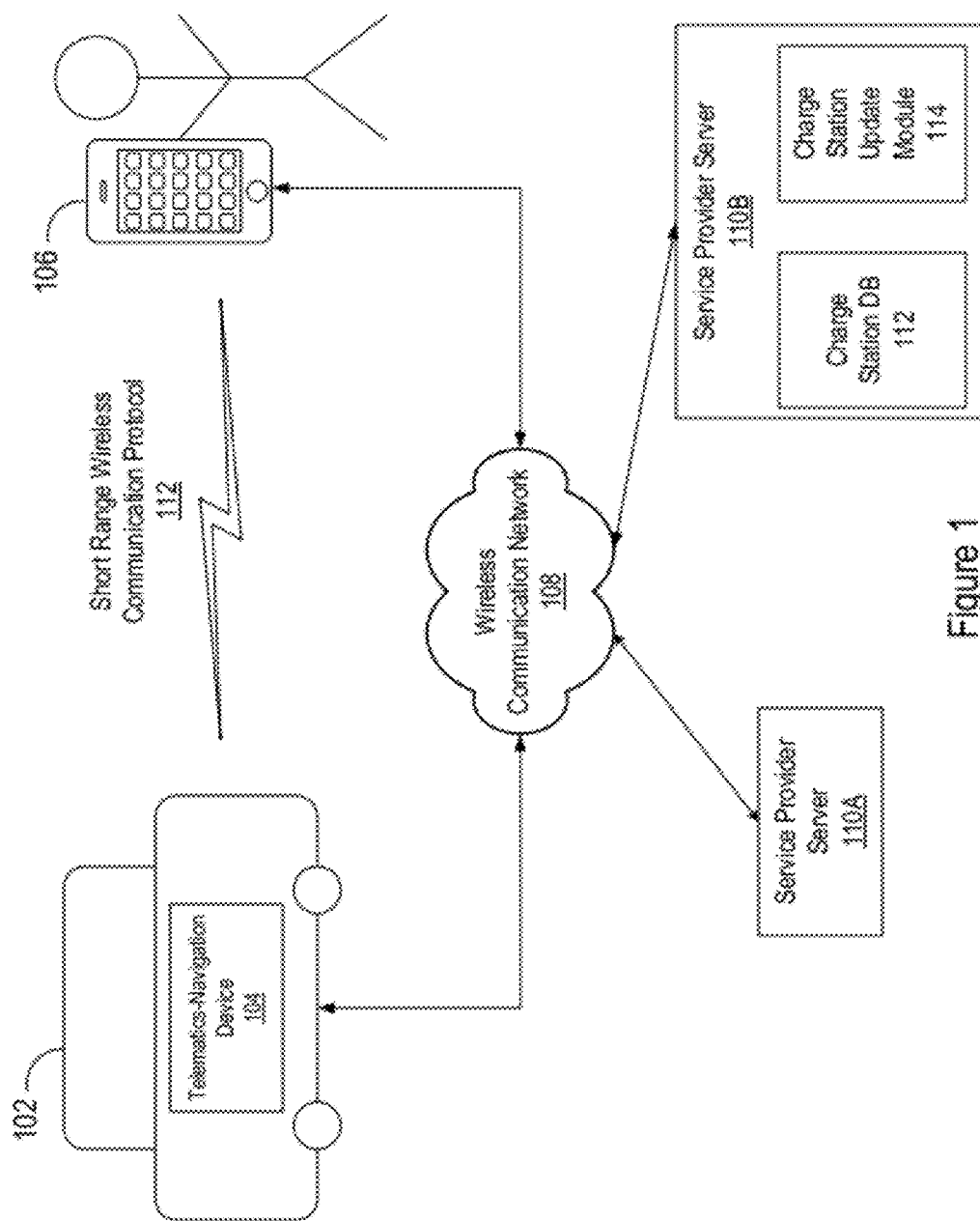


Figure 1

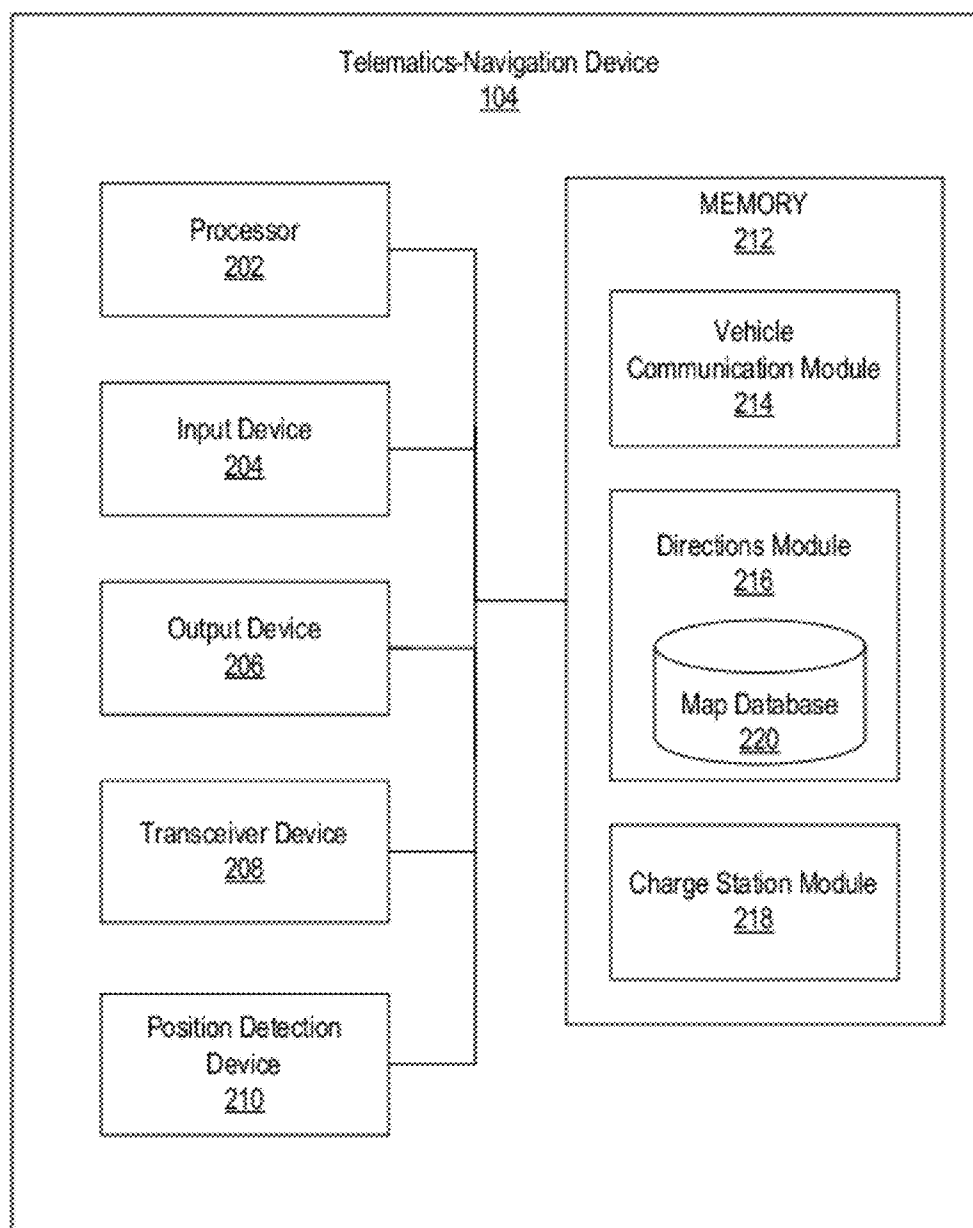


Figure 2

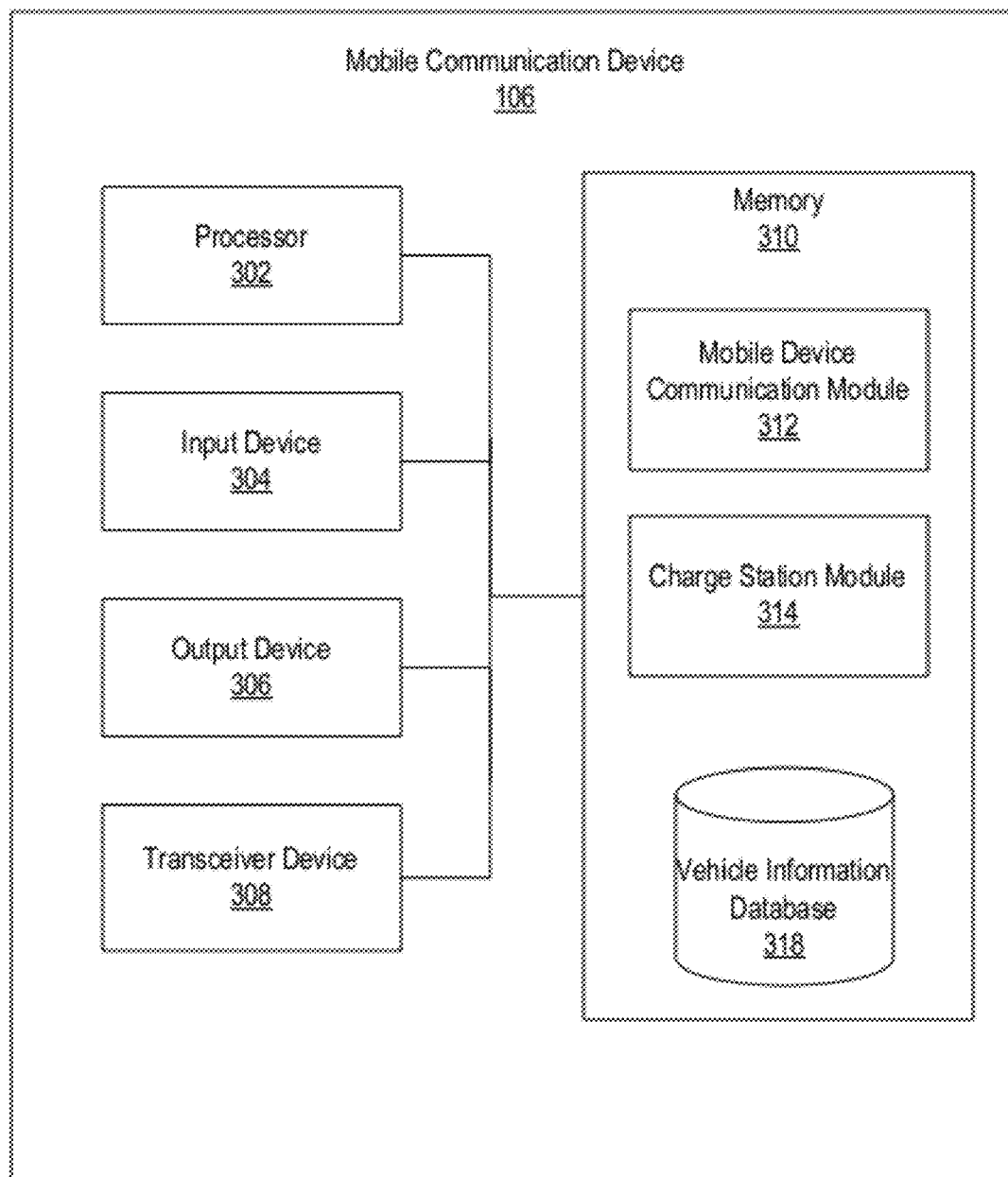


Figure 3

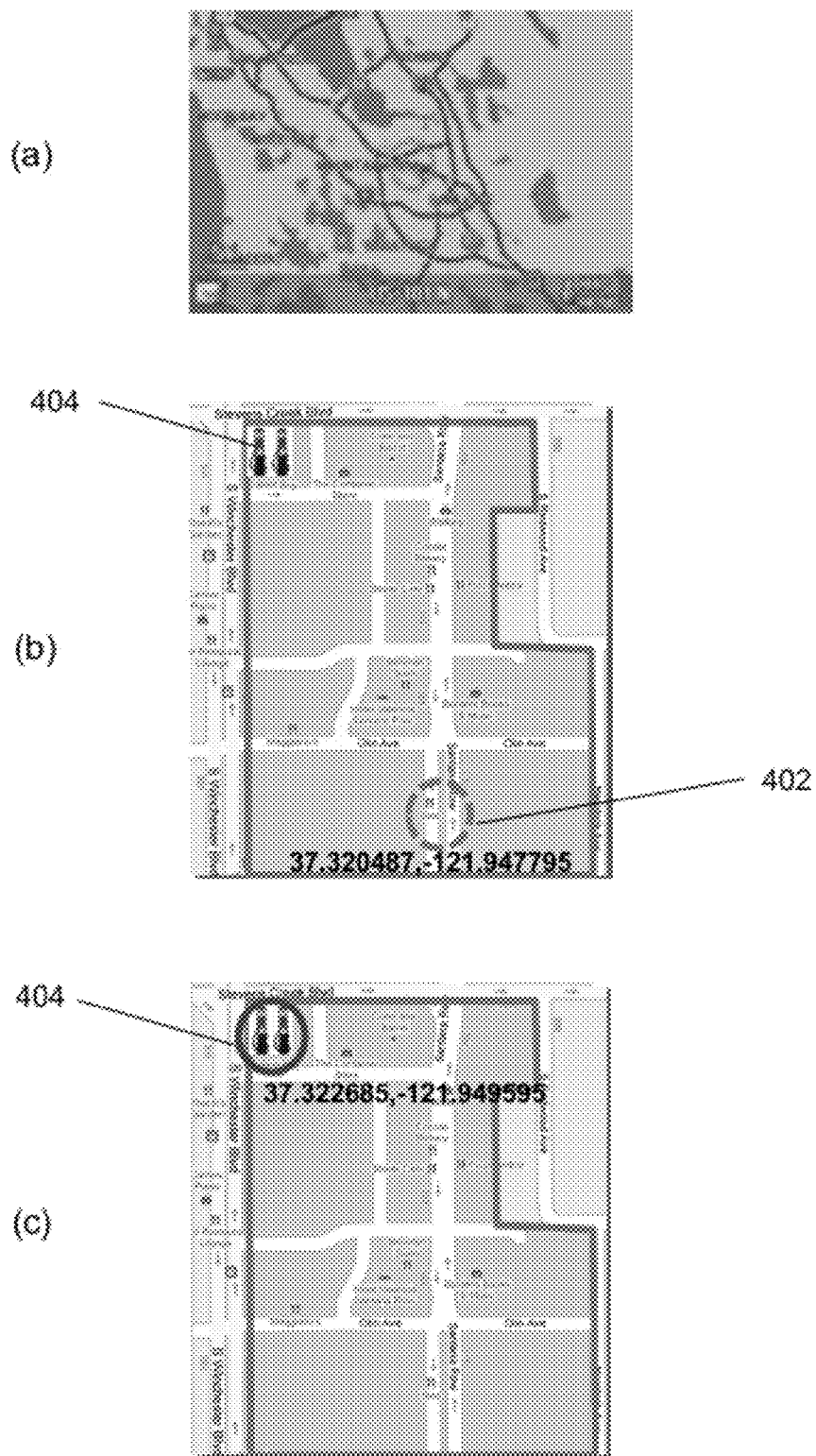


Figure 4

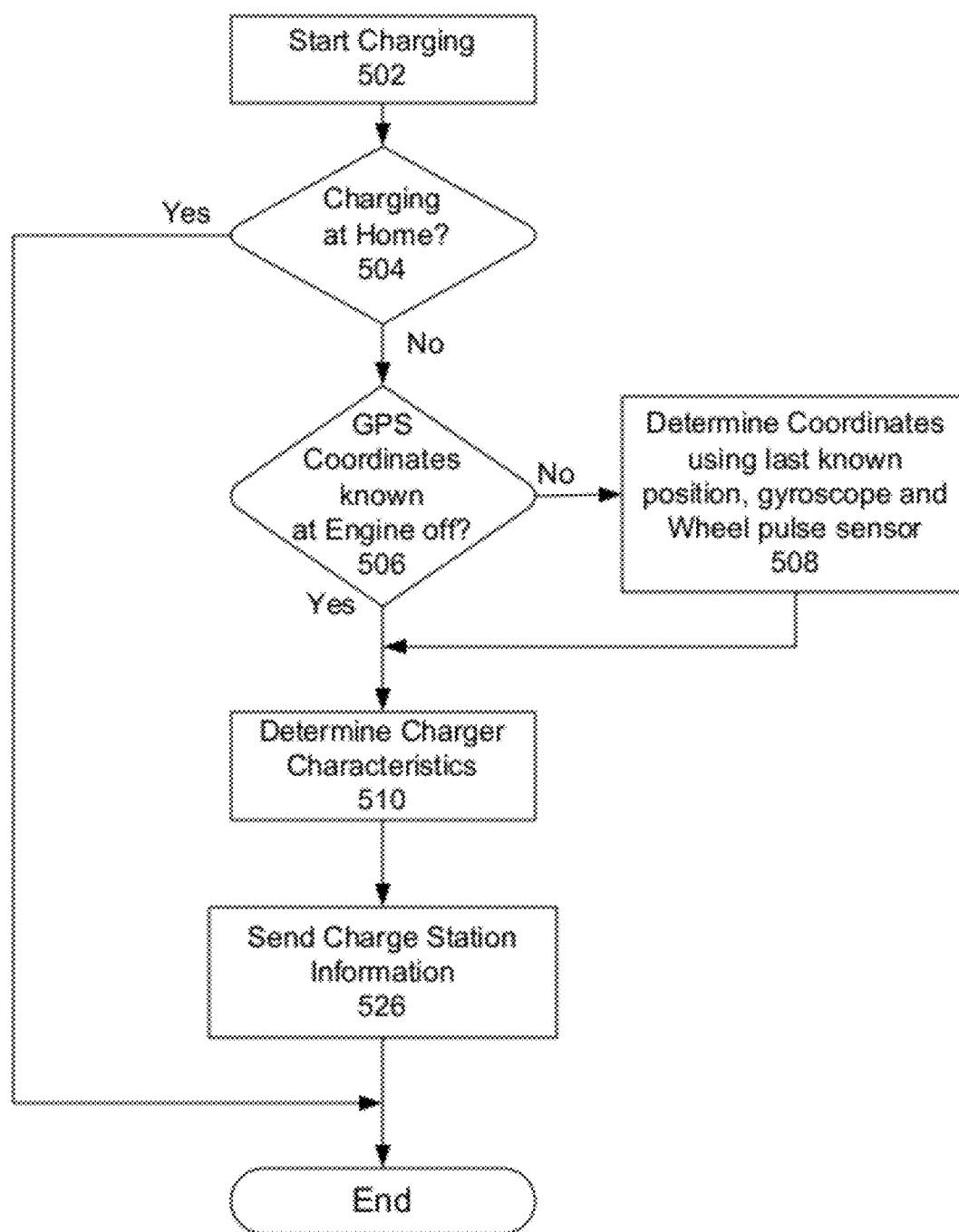


Figure 5

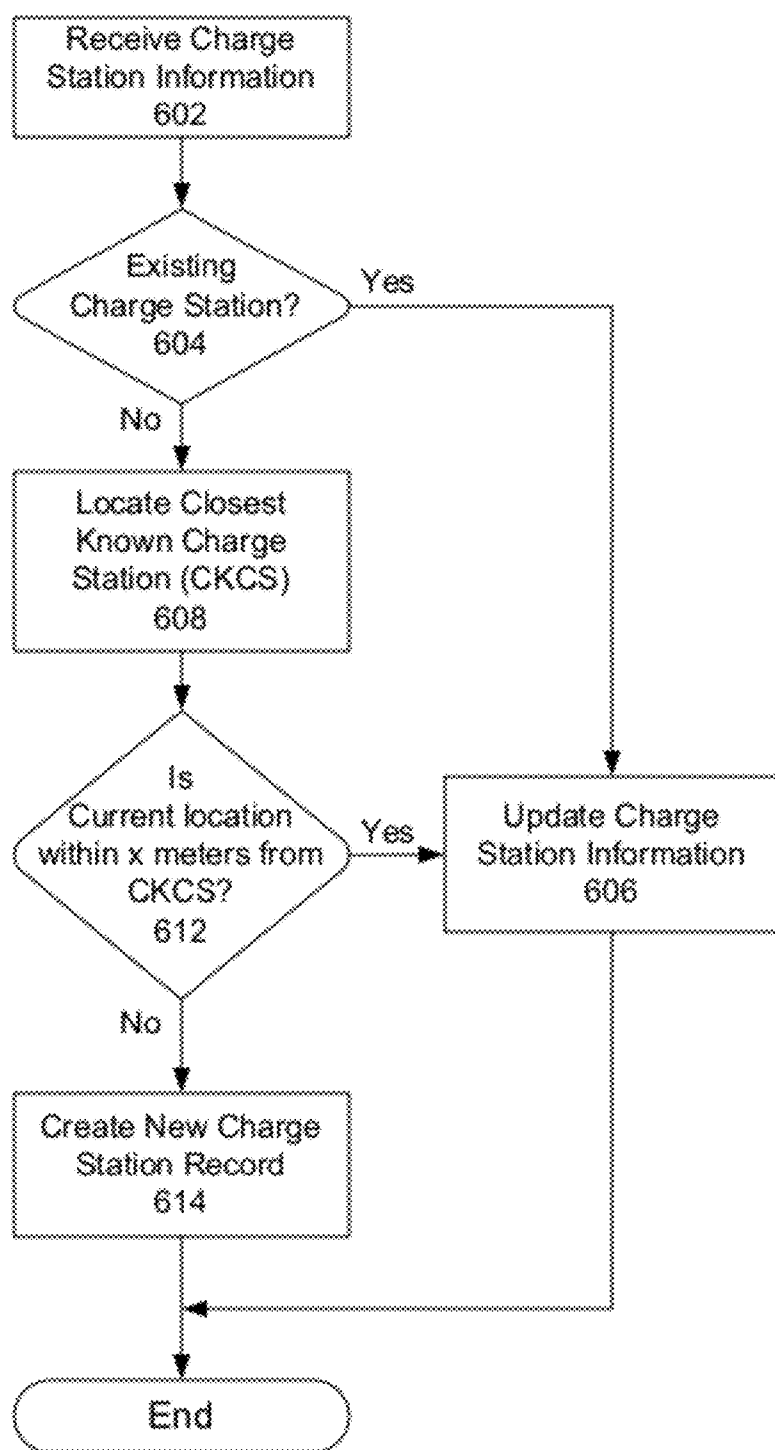


Figure 6

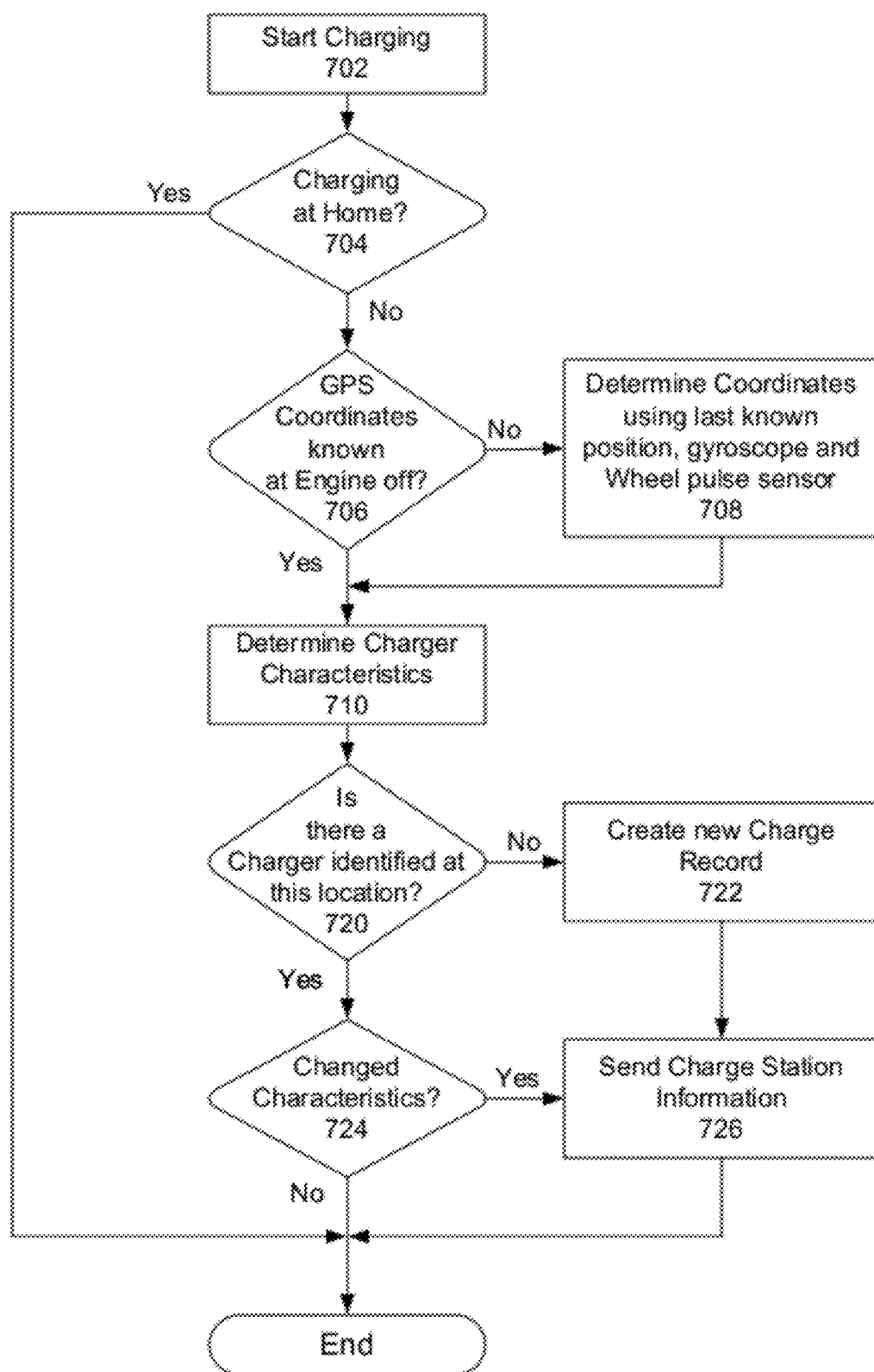


Figure 7

SYSTEM AND METHOD FOR UPDATING CHARGE STATION INFORMATION

RELATED APPLICATIONS

[0001] This application claims priority to U.S. Provisional application 61/414,396 filed on Nov. 16, 2010 by Okino et al. which is incorporated by reference herein in its entirety.

BACKGROUND

[0002] Electric vehicles are vehicles that use one or more electric motors for propulsion of the vehicle. The electric motors are powered by rechargeable batteries on-board the vehicle. Because electric vehicles are powered by on-board batteries, their driving range is limited by the amount of charge in their batteries. When a vehicle's batteries get low on charge, the vehicle can be recharged at a charging station. However, currently there is a limited number of charging stations for electric vehicles. The embodiments described herein show an improved methodology to identify charging location and to route a vehicle to a charging station.

BRIEF DESCRIPTION OF THE DRAWINGS

[0003] FIG. 1 is a high-level block diagram of a vehicle communication environment according to one embodiment.

[0004] FIG. 2 is a high-level block diagram illustrating a detailed view of a telematics-navigation device according to one embodiment.

[0005] FIG. 3 is a high-level block diagram illustrating a detailed view of a mobile device according to one embodiment.

[0006] FIG. 4 is an illustration of embodiments in which the location of the charging station is different from the location identified by a vehicle's navigation system for the point of interest in which the charging station resides.

[0007] FIG. 5 is a flowchart of a method for determining characteristics of a charging station by a vehicle in accordance with one embodiment.

[0008] FIG. 6 is a flowchart of a method for updating a charging station database in a remote server and/or in the vehicle in accordance with one embodiment.

[0009] FIG. 7 is a flowchart of a method for determining characteristics of a charging station by a vehicle in accordance with one embodiment.

[0010] The figures depict various embodiments of the present embodiments for purposes of illustration only. One skilled in the art will readily recognize from the following discussion that alternative embodiments of the structures and methods illustrated herein may be employed without departing from the principles of the embodiments described herein.

DETAILED DESCRIPTION

[0011] Embodiments are now described with reference to the figures where like reference numbers indicate identical or functionally similar elements. In the figures, a letter after a reference numeral, such as "110A," indicates that the text refers specifically to the element having that particular reference numeral. A reference numeral in the text without a following letter, such as "110," refers to any or all of the elements in the figures bearing that reference numeral (e.g., "110" in the text refers to reference numerals "110A," and/or "110B" in the figures). Also in the figures, the left most digits of each reference number correspond to the figure in which the reference number is first used.

[0012] FIG. 1 is a high-level block diagram of a vehicle communication environment 100 according to one embodiment. FIG. 1 illustrates an electric vehicle (EV) 102, a mobile device 106, and service provider servers 110 connected by a wireless communication network 108. The service provider servers 110 can include in its memory a charge station database 112 and a charge station update module 114.

[0013] The electric vehicle 102 represents a vehicle that contains one or more electric motors for propulsion of the vehicle 102. The electric motors are powered by rechargeable batteries on-board the vehicle 102. The on-board batteries are charged when the vehicle 102 is connected to an outside power source. For example, the batteries may be charged by connecting the vehicle 102 to a charging station that draws power from a power grid. The on-board batteries may also be charged using regenerative braking or by other techniques or systems that may be part of the vehicle 102. In one embodiment, the electric vehicle 102 is purely electric in that it only has an electric motor. In another embodiment, the electric vehicle 102 has both an electric motor and internal combustion engine. In some embodiments, the electric vehicle 102 may have any number of electric motors (e.g., an electric motor at each wheel, on select wheels, or in other configurations) and/or internal combustion engines and they may operate in series (e.g., as in an extended range electric vehicle), in parallel, or some combination of series and parallel operation.

[0014] The electric vehicle 102 includes a telematics-navigation device 104, in some embodiments the telematics unit does not include navigation functionality. The telematics-navigation device 104 represents a device that exchanges information with entities coupled to the wireless communication network 108 and with entities that are within range of a short range wireless communication protocol 112. The telematics-navigation device 104 can communicate with a mobile device 106 via the short range wireless communication protocol 112. The short range wireless communication protocol 112 is a protocol that uses short radio wavelengths to exchange data over short distances. Therefore, the communication range of the protocol 112 is limited. In one embodiment, the short range wireless communication protocol 112 is Bluetooth®. In some embodiments other types of point-to-point or network-enabled communication are used. For example, WiMax may be used as a point to point communication protocol with a range of miles.

[0015] The mobile device 106 represents a portable device that can be carried by the driver of the electric vehicle 102 when in the vehicle 102 and when the driver is away from the vehicle 102. The mobile device 106 is configured to communicate via the wireless communication network 108 and the short range wireless communication protocol 112. Examples of a mobile device (MD) 106 include a cellular phone, personal device assistant (PDA), smart phone, pocket personal computer (PC), laptop computer, smart watch or other devices having a processor, communications capability and are easily transportable, for example. In some embodiments the vehicle 102 can communicate with the wireless communication network via the mobile device 106.

[0016] Returning to FIG. 1, the service provider servers 110A and 110B represent entities that perform services for the electric vehicle 102 and/or the mobile device 106. In one embodiment, the service provider servers 110 provide information to electric vehicle 102 and the mobile device 106 to allow them to perform certain functions. For example, the service provider servers 110 may provide the vehicle 102 and

the mobile device **106** with charge station information, traffic information, weather information, road condition information, map information, location information, and driving directions that the vehicle **102** and/or the mobile device **106** may display or use to perform other operations. Although only two service provider servers **110** are shown in FIG. 1, any number of service provider servers **110** can be connected to the wireless communication network **108**.

[0017] The wireless communication network **108** represents a communication pathway between the electric vehicle **102**, the mobile device **106**, and the service provider servers **110**. In one embodiment, the wireless communication network **108** is a cellular network comprised of multiple base stations, controllers, and a core network that typically includes multiple switching entities and gateways. In one embodiment, the wireless communication network **108** is a wireless local area network (WLAN) that provides wireless communication over a limited area. In one embodiment, the WLAN includes an access point that connects the WLAN to the Internet. The wireless communication network **108** can include satellites.

[0018] FIG. 2 is a high-level block diagram illustrating a detailed view of the telematics-navigation device **104** according to one embodiment. The telematics-navigation device **104** includes a processor **202**, an input device **204**, an output device **206**, a transceiver device **208**, a position detection device **210**, and a memory **212**.

[0019] The processor **202** processes data signals and may comprise various computing architectures including a complex instruction set computer (CISC) architecture, a reduced instruction set computer (RISC) architecture, or an architecture implementing a combination of instruction sets. Although only a single processor is shown in FIG. 2, multiple processors may be included. The processor **202** comprises an arithmetic logic unit, a microprocessor, a general purpose computer, or some other information appliance equipped to transmit, receive and process electronic data signals from the memory **212**, the input device **204**, the output device **206**, the transceiver device **208**, or the position detection device **210**.

[0020] The input device **204** is any device configured to provide user input to the telematics-navigation device **104** such as, a cursor controller or a keyboard. In one embodiment, the input device **204** can include an alphanumeric input device, such as a QWERTY keyboard, a key pad or representations of such created on a touch screen, adapted to communicate information and/or command selections to processor **202** or memory **212**. In another embodiment, the input device **204** is a user input device equipped to communicate positional data as well as command selections to processor **202** such as a joystick, a mouse, a trackball, a stylus, a pen, a touch screen, cursor direction keys or other mechanisms to cause movement adjustment of an image.

[0021] The output device **206** represents any device equipped to display electronic images and data as described herein. Output device **206** may be, for example, an organic light emitting diode display (OLED), liquid crystal display (LCD), cathode ray tube (CRT) display, or any other similarly equipped display device, screen or monitor. In one embodiment, output device **206** is equipped with a touch screen in which a touch-sensitive, transparent panel covers the screen of output device **206**. In one embodiment, the output device **206** is equipped with a speaker that outputs audio as described herein.

[0022] The transceiver device **208** represents a device that allows the telematics-navigation device **104** to communicate with entities via the wireless communication network **108** and the short range wireless communication protocol **112**. The transceiver device **208** is used by the telematics-navigation device **104** to communicate with the mobile device **106** and the service provider servers **110**. Although a single transceiver device **208** is shown, it should be understood that the telematics-navigation device **104** may include multiple transceiver devices. For example, one transceiver device may be configured to communicate via the wireless communication network **108** and another transceiver device may be configured to communicate via that short range protocol **112**. In one embodiment, the transceiver device **208** is for one or more of the following communications: infrared communication, IEEE 802.11a/b/g/n/p communication, 3 G communication, 3GPP Long Term Evolution (LTE), IEEE 802.16 (or WiMax) communication, or radio frequency communication. It is envisioned that other protocols can also be used.

[0023] In one embodiment, the short range wireless communication protocol **112** is Bluetooth® and the transceiver device **208** is used for Bluetooth communication. The communication range of the transceiver device **208** via Bluetooth is limited. Typically the communication range via Bluetooth is up to 100 meters depending on the transceiver device **208** and obstacles. The transceiver device **208** only communicates via Bluetooth with devices with which it has established a connection. A connection with a device will last as long as the device is within range or until one of the devices terminates the connection.

[0024] Typically, the first time a connection is being established between two devices, the devices must be paired. The pairing process is started by a first device making its Bluetooth link visible to the second device. The second device identifies the first device and sends a connection request to the first device. If the request is accepted by the first device, a link key is created for their connection and stored by both devices. Once the link key has been stored by both devices, the pairing process is complete and data can be exchanged via Bluetooth. Two devices that have been paired can automatically establish a connection with each other when in range of each other. Here, the telematics-navigation device **104** is paired with the mobile device **106** of the electric vehicle's driver. If multiple drivers use the electric vehicle **102**, the telematics-navigation device **104** may be paired with each of the driver's mobile device. It is envisioned that other pairing methods can be used.

[0025] The position detection device **210** represents a device that communicates with a plurality of positioning satellites (e.g., GPS satellites) to determine the geographical location of the electric vehicle **102**. In one embodiment, to determine the location of the vehicle **102**, the position detection device **210** searches for and collects GPS information or signals from four or more GPS satellites that are in view of the position detection device **210**. Using the time interval between the broadcast time and reception time of each signal, the position detection device **210** calculates the distance between the vehicle **102** and each of the four or more GPS satellites. These distance measurements, along with the position and time information received in the signals, allow the position detection device **210** to calculate the geographical location of the vehicle **102**. In alternative embodiments, systems and/or techniques other than position satellites may be used to determine a position of a vehicle. As examples, trian-

gulation of cell phone towers or optical recognition of street signs may be used to determine a location. Additional techniques are set forth herein.

[0026] The memory **212** stores instructions and/or data that may be executed by processor **202**. The instructions and/or data may comprise code for performing any and/or all of the techniques described herein. Memory **212** may be a dynamic random access memory (DRAM) device, a static random access memory (SRAM) device, Flash RAM (non-volatile storage), combinations of the above, or some other memory device known in the art. The memory **212** comprises a vehicle communication module **214**, a directions module **216**, and a charge station module **218**. The modules are adapted to communicate with the processor **202**, the input device **204**, the output device **206**, the transceiver device **208**, and/or the position detection device **210**.

[0027] The directions module **216** provides a user of the electric vehicle **102** with driving directions to a destination. When a request is received from a user for directions to a destination, the directions module **216** obtains from the position detection module **210** the current geographic location of the vehicle **102**. Based on the current location and the destination, the directions module **216** retrieves a vector map from a map database **220**. The map database **220** includes multiple vector maps. In one embodiment, the vector maps identify the locations of charging stations and other establishments/points of interest (POI), e.g., restaurants, stores, schools, hospitals, and banks.

[0028] The directions module **216** locates the current location and the destination in the map. The directions module **216** identifies multiple routes from the current location to the destination. In one embodiment, the directions module **216** selects one of the routes based on user criteria, such as the fastest route, the shortest route, the least congested route, the most energy efficient route, street route, and highway route. In one embodiment, the directions module **216** uses information (e.g., traffic and weather information) from one or more service provider servers **110** to select a route. In another embodiment, the directions module **216** presents the identified routes to the user and allows the user to select a route. The directions module **216** provides directions through the output device **206** on how to get to the destination via the selected route.

[0029] The charge station module **218** includes information related to charge stations including location information including address and/or geographic coordinates, availability (operational, reservations), compatibility information, e.g., connector types, charge type (standard, fast, etc.). In alternate embodiments this information can be part of the map database **220**. The discussion herein can therefore also apply to updating the map database **220**.

[0030] FIG. 3 is a high-level block diagram illustrating a detailed view of the mobile device **106** according to one embodiment. The mobile device **106** includes a processor **302**, an input device **304**, an output device **306**, a transceiver device **308**, and a memory **310**.

[0031] The processor **302**, input device **304**, output device **306** and transceiver device **308** of the mobile device **106** have similar functionality to the processor **202**, input device **204**, output device **206** and transceiver device **208** of the telematics-navigation device **104**. Therefore, for purposes of brevity a functional description of these devices is omitted.

[0032] Additionally, the memory **310** of the mobile device **106** has similar functionality to the memory **210** of the

telematics-navigation device **104**. However, the memory **310** of the mobile device **106** includes different modules than those of the telematics-navigation device **104**. The memory **310** of the mobile device **106** includes a mobile device communication module **312**, a charge station module **314** and a vehicle information database **318**. The modules are adapted to communicate with the processor **302**, input device **304**, output device **306** and transceiver device **308**.

[0033] When driving an electric vehicle **102** a common concern when leaving the house is will the driver make it to his/her destination. In situations where the driver is concerned about whether the vehicle's current state of charge (SOC) will enable it to reach the destination, the electric vehicle **102** can identify nearby charging stations and can generate a route to a charging station.

[0034] Conventional systems update vehicle map databases **220** periodically by, for example, annually releasing a new database, e.g., on DVDs. The database manufacturer may need to visit the POIs such as charging stations to confirm the accuracy of the location and related information which introduces additional delay and costs in generating an updated database. Even with such precautions, these updates are outdated immediately. Inaccurate/outdated charging station locations may present problems if drivers rely on such locations and accordingly drive to an incorrect location because of an error in the address or because the geographic coordinates of the point of interest (POI) is different from the geographic coordinates of the charge station, e.g., in the example illustrated in FIG. 4.

[0035] If the state of charge (SOC) of the vehicle is substantially depleted, having inaccurate coordinates can result in the vehicle exhausting the charge and requiring towing in order to reach the charging station. In addition outdated databases may include inaccurate charging station information, e.g., the types of charging connector types, which may also result in a vehicle exhausting its power supply before reaching a proper charging station.

[0036] FIG. 4 is an illustration of embodiments in which the location of the charging station is different from the location identified by a vehicle's navigation system for the point of interest in which the charging station resides. As described above, the directions module **216** locates the current location and the destination in the map **220**. The directions module **216** identifies multiple routes from the current location to the destination.

[0037] The locations of charging stations can be stored in the vehicle itself, e.g., in the charge station module **218** or map database **220**, and/or the vehicle can access the locations via its telematics unit by connecting to a remote server **110**. The vehicle can identify those charging stations that are within the range of the vehicle. For example if the electric vehicle has a remaining range of 60 miles but the vehicle is 90 miles from the ultimate destination, the vehicle can identify those charging stations within the 60 mile range and can also identify those charging stations that require the shortest detour from the planned path. In an embodiment, the directions module **216** identifies a route that enables the vehicle to reach the charging station with the least disruption from the planned path and can also identify how long the electric vehicle **102** needs to recharge in order to complete the trip to the destination. As described herein, this recharging time can be based upon, for example, the maximum charge available, efficiency of the charging station and the status of the vehicle's battery.

[0038] In another embodiment, the vehicle's navigation system/directions module 216 can route the driver along the path to the ultimate destination and suggest various charging locations along the way. The vehicle can also check the availability of various charging stations and provide the driver (or route the vehicle) to those charging stations with available charging ports.

[0039] There may be a situation where a vehicle's navigation system/directions module 216 is directing the driver to a charging station but the charging station is in a location where there is no GPS signal or cell phone signal or is in a location remote from the address of the point of interest's address. Therefore, while the driver may successfully arrive at the garage or point of interest, there may be a problem directing the driver to the actual charging station. FIG. 4(a) illustrates a display in the vehicle that shows the location of a charging station, e.g., at the Santana Row Mall in San Jose, Calif. FIG. 4(a) is a small scale map showing this location. The Santana Row Mall may have an address stored in the map database 220 of "368 Santana Row, San Jose, Calif." This location 402 has geographic coordinates of (37.320487, -121.947795) as illustrated in FIG. 4(b) with a scale much larger than the scale of FIG. 4(a). However, as shown in FIG. 4(b) the location 404 of the charging stations is remote from the location 402 of the POI. A driver attempting to locate the charging station needs more precision about the location of the charging station than is provided merely by the having the address of the POI. As shown in FIG. 4(c) the charging stations have geographic coordinates of (37.322685, -121.949595). In addition, charging stations are only compatible with certain vehicles, due to, for example, outlet connection types, a benefit of the embodiments is that this information is identified either directly via the "characteristics" of the charging station or indirectly, since the type of connection in the vehicle is known the charge station database will include the type of connections and/or compatibility with vehicles and the embodiments can have the option of only displaying charge stations that are compatible to the vehicle.

[0040] FIG. 5 is a flowchart of a method for determining characteristics including the location of a charging station by a vehicle in accordance with one embodiment. A purpose of this procedure is to identify new charging stations or to update the identified characteristics of existing charging stations in a charging station database stored, for example, in the charging station module 218 and/or a remote server 110. When a vehicle reaches a charging station and starts 502 charging, the vehicle determines 504 whether the vehicle is charging at home. This can be based upon last known GPS coordinates, type of charger etc. If the charging station is the user's home station, i.e., a private charging station, then the process can end since, in an embodiment, private/home charging stations need not be included in the charging station database in the charging station module 218 and/or remote server 110. If 504 the charging station is not at the driver's home (or otherwise identified as a private charging station) then the charge station module 218 (or other software) determines 506 whether the GPS (geographic) coordinates of the vehicle were known when the engine was turned off. If 506 the geographic coordinates were known, then the vehicle determines 510 charging station characteristics such as the connector type, charge voltage (standard/fast/other), location, and/or availability. The charging station information, including the location can be sent 526 and stored as part of a charge station database in the charge station module 218 and/or transmitted 526 to a

central server 110 that includes a charge station database 112. This transmission 526 (or 726) can occur while charging or at a later time, e.g., after the vehicle's engine is started. Additional details about the central server 110 is set forth herein.

[0041] In an alternate embodiment, the location of the charging station can be determined by identifying the change in location, e.g., distance, direction and elevation, occurring after the vehicle connection to the charging station is removed, for example, after the vehicle is re-started and moves. The change of distance determination can be done in a manner similar to that described herein with respect to steps 508 or 708, using the gyroscope and wheel pulse sensor, for example. When the GPS signals are again available to the vehicle, the charge station location can be determined by modifying the location identified by the GPS signals with the determined change in location information. In embodiments, the charge station location is estimated using the location of the vehicle, this estimate is satisfactory since the vehicle is connected to the charge station. In this embodiment, the vehicles are probes to accurately identify and verify charge station locations and characteristics.

[0042] If 506 the GPS coordinates of the vehicle were not known when the engine was turned off, then the position detection device 210 uses the last known GPS position and then estimates 508 the current position of the vehicle based upon gyroscope readings which can provide directional information and elevation information along with wheel pulse information which can provide distance information and turning information. It is envisioned that additional vehicle sensor information can be used to assist in estimating the current position of the vehicle. In another embodiment, triangulation of cell phone towers or optical recognition of street signs may also be used to assist in determining the current location. In some embodiment the charge stations are networked, so connections may be made directly between the vehicle and the networked charge station, e.g., using a Bluetooth connection. As described above, the GPS coordinates of the vehicle may not be available if a vehicle is in a covered parking garage/area or the GPS system is inoperative.

[0043] FIG. 6 is a flowchart of a method for updating a charging station database in a remote server 110 and/or in the vehicle in accordance with one embodiment. In an embodiment the charge station information transmitted in step 526 (or step 726) is received by the charge station module 218 and/or the remote server 110 and the charging station databases in the charge station module 218 and/or the remote server 110 is updated. For ease of discussion, the following description will be described with reference to the updating of the charge station database 112 in the remote server 110. The remote server 110 receives 602 the charge station information. The charge station update module 114 determines 604 whether the charge station information corresponds to a charge station already existing in the charge station database 112. This determination can check one or multiple parameters of the charge station such as the location of the charge station, the connector type, charge voltage, availability, compatibility, etc. If 604 the charge station information corresponds to an existing charge station then the charge station update module 114 updates 606 the charge station database 112 with the information, possibly including a timestamp and vehicle identifier from which the updated information was received.

[0044] If 604 the charge station information does not correspond to an existing charge station then the charge station update module 114 locates/identifies 608 the closest known

charge station and determines the distance between the closest known charging station and the newly identified charge station. In one embodiment, the charge station update module compares the current charging station with those having similar characteristics in the database, e.g., having similar connector types, charge voltage, etc. In other embodiments, the comparison is with all charging stations. If **612** the distance is less than a threshold, e.g., 5-50 meters, then the charge station update module **114** presumes that the charge station is the same as the closest known charge station and updates **606** the charge station information database **112** based upon the information received in step **602**.

[0045] If **612** the distance is more than a threshold then the charge station update module **114** presumes that it has received information for a new charge station and creates **614** a new charging station record in the charge station database **112** based upon the information received in step **602**.

[0046] In an embodiment, the charge station database **112** includes a verification protocol in which the database **112** is updated after receiving similar information from multiple vehicles or from a single vehicle multiple times. The number of times/vehicles similar information must be received in order to satisfy the verification protocol can vary. In an embodiment, the first time new information is received, before updating **606** charge station information or creating **614** a new charge station record, the information can be stored in a related database, or a related record of the charge station database **114** along with a counter indicating the number of times similar information has been received. Once the counter reaches the threshold in the verification protocol the charge station information can be updated **606** or a new charge station record can be created **614**.

[0047] FIG. 7 is a flowchart of a method for determining characteristics of a charging station by a vehicle in accordance with one embodiment. FIG. 7 is an alternate embodiment to the method set forth in FIG. 5. When a vehicle reaches a charging station and starts **702** charging, the vehicle determines **704** whether the vehicle is charging at home. As described above, this can be based upon last known GPS coordinates, the type of charger, etc. If **704** the charging station is the user's home station, i.e., a private charging station, then the process can end as in an embodiment, private/home charging stations need not be included in the charging station database in the charging station module **218** and/or remote server **110**. If **704** the charging station is not at the driver's home (or, for example, otherwise identified as a private charging station) then the charge station module **218** (or other software) determines **706** whether the GPS (geographic) coordinates of the vehicle were known when the engine was turned off.

[0048] If **706** the GPS coordinates of the vehicle were not known when the engine was turned off, then the position detection device **210** uses the last known GPS position and estimates **708** the current position of the vehicle based upon gyroscope readings which can provide directional information and elevation information along with wheel pulse information which can provide distance information and turning information. As described above, it is envisioned that additional vehicle sensor information can be used to assist in estimating the current position of the vehicle. In another embodiment, triangulation of cell phone towers or optical recognition of street signs may also be used to assist in determining the current location. The process then continues with step **710**.

[0049] If **706** the geographic coordinates were known when the engine was turned off, then the vehicle determines **710** the charging station characteristics such as the connector type, charge voltage (standard/fast/other), location, and/or availability. The information, including the location can be stored as part of a charge station database in the charge station module **218** and/or transmitted to a central server **110** that includes a charge station database. Additional details about the central server **110** is set forth herein. In order to reduce communication traffic between the vehicle and the remote server **110**, in this embodiment an update is sent when there is a change to the database. The charge station module **218** then determines **720** whether the charger characteristics correspond to an existing charge station. This determination **720** can be based on the geographic coordinates. If the charge station module **218** determines **720** that no charging station is at or near the geographic location determined based on the GPS coordinates at engine off or by the process outlined above in step **708**, then the charge station module **218** can, optionally, create **722** a new charge station record and send **726** the charge station record and related information to the charge station update module **114** and/or can update the vehicle's charge station database.

[0050] If the charge station module **218** determines **720** that the geographic location corresponds to an existing charging station then the charge station module **218** can, determine whether **724** any of the charger characteristics have changed by comparing the determined charge station characteristics to the characteristics stored in the charging station database in the vehicle's memory **212**. If **724** any of the charger characteristics have changed then the charge station module **218** can send **726** the charge station information to the charge station update module **114** and/or can update the vehicle's charge station database.

[0051] Reference in the specification to "one embodiment" or to "an embodiment" means that a particular feature, structure, or characteristic described in connection with the embodiments is included in at least one embodiment. The appearances of the phrase "in one embodiment" in various places in the specification are not necessarily all referring to the same embodiment.

[0052] Some portions of the detailed description are presented in terms of algorithms and symbolic representations of operations on data bits within a computer memory. These algorithmic descriptions and representations are the means used by those skilled in the data processing arts to most effectively convey the substance of their work to others skilled in the art. An algorithm is here, and generally, conceived to be a self-consistent sequence of steps (instructions) leading to a desired result. The steps are those requiring physical manipulations of physical quantities. Usually, though not necessarily, these quantities take the form of electrical, magnetic or optical signals capable of being stored, transferred, combined, compared and otherwise manipulated. It is convenient at times, principally for reasons of common usage, to refer to these signals as bits, values, elements, symbols, characters, terms, numbers, or the like. Furthermore, it is also convenient at times, to refer to certain arrangements of steps requiring physical manipulations of physical quantities as modules or code devices, without loss of generality.

[0053] However, all of these and similar terms are to be associated with the appropriate physical quantities and are merely convenient labels applied to these quantities. Unless specifically stated otherwise as apparent from the following

discussion, it is appreciated that throughout the description, discussions utilizing terms such as “processing” or “computing” or “calculating” or “determining” or “displaying” or the like, refer to the action and processes of a computer system, or similar electronic computing device, that manipulates and transforms data represented as physical (electronic) quantities within the computer system memories or registers or other such information storage, transmission or display devices.

[0054] Certain aspects of the embodiments include process steps and instructions described herein in the form of an algorithm. It should be noted that the process steps and instructions of the embodiments could be embodied in software, firmware or hardware, and when embodied in software, could be downloaded to reside on and be operated from different platforms used by a variety of operating systems.

[0055] The embodiments also relates to an apparatus for performing the operations herein. This apparatus may be specially constructed for the required purposes, or it may comprise a general-purpose computer selectively activated or reconfigured by a computer program stored in the computer. Such a computer program may be stored in a transitory or non-transitory computer readable storage medium, such as, but is not limited to, any type of disk including floppy disks, optical disks, CD-ROMs, magnetic-optical disks, read-only memories (ROMs), random access memories (RAMs), EPROMs, EEPROMs, magnetic or optical cards, application specific integrated circuits (ASICs), or any type of media suitable for storing electronic instructions, and each coupled to a computer system bus. Furthermore, the computers referred to in the specification may include a single processor or may be architectures employing multiple processor designs for increased computing capability.

[0056] The algorithms and displays presented herein are not inherently related to any particular computer or other apparatus. Various general-purpose systems may also be used with programs in accordance with the teachings herein, or it may prove convenient to construct more specialized apparatus to perform the required method steps. The required structure for a variety of these systems will appear from the description herein. In addition, the embodiments are not described with reference to any particular programming language. It will be appreciated that a variety of programming languages may be used to implement the teachings of the embodiments as described herein, and any references herein to specific languages are provided for disclosure of enablement and best mode of the embodiments.

[0057] In addition, the language used in the specification has been principally selected for readability and instructional purposes, and may not have been selected to delineate or circumscribe the inventive subject matter. Accordingly, the disclosure of the embodiments is intended to be illustrative, but not limiting, of the scope of the embodiments.

[0058] While particular embodiments and applications have been illustrated and described herein, it is to be understood that the embodiments are not limited to the precise construction and components disclosed herein and that various modifications, changes, and variations may be made in the arrangement, operation, and details of the methods and apparatuses of the embodiments without departing from the spirit and scope of the embodiments.

What is claimed is:

1. A system for identifying charge station locations comprising: a vehicle including:

a connector for coupling said vehicle to a charge station;
a location determination system to determine the charge station location based upon a location of the vehicle when said connector is coupled to said charge station; and

a transmission device for transmitting said charge station location to a remote charge station database.

2. The system of claim 1, wherein said location determination system comprises:

a location signal receiver capable of receiving location signals; and

a position estimation device using a distance measuring device and an elevation determination device to determine a change in location based upon movement after the location signals are no longer received, and determining a charge station location by determining the location of the vehicle when the connector is coupled to the charge station based upon said location signals and the change in location determination.

3. The system of claim 2, wherein said distance measuring device includes a wheel pulse unit for determining a distance traveled based upon wheel rotation and said elevation determination device includes a gyroscope.

4. The system of claim 1, further comprising:

a charge station characteristic device for determining charge station characteristics including at least one of charging rate or connection type;

wherein said transmission device transmits said charge station characteristics to the remote charge station database.

5. The system of claim 1, further comprising:

a remote server including:

said remote charge station database; and

an update module for updating said charge station database with information about a new charge station when said received charge station location does not substantially match an existing charge station in said charge station database.

6. The system of claim 1, wherein said location signals are GPS signals.

7. A method for identifying charge station locations comprising the steps of:

coupling a vehicle to a charge station;

determining the charge station location based upon a location of the vehicle when said connector is coupled to said charge station; and

transmitting, by said vehicle, said charge station location to a remote charge station database.

8. The method of claim 7, wherein said step of determining the charge station location further comprises the steps of:

receiving location signals; and

determining a change in location of said vehicle based upon movement occurring after said location signals are no longer received, and determining a charge station location by determining the location of the vehicle when the connector is coupled to the charge station based upon said location signals and said change in location determination.

9. The method of claim 8, wherein the step of determining a change in location includes the steps of:

measuring the distance traveled using wheel rotation measurements and

measuring changes in direction and elevation using gyroscope measurements.

10. The method of claim 7, further comprising the steps of: determining charge station characteristics including at least one of charging rate or connection type; and transmitting said charge station characteristics to the remote charge station database.
11. The method of claim 7, further comprising the steps of: receiving said charge station information at a remote server, and
updating said charge station database with information about a new charge station when said received charge station location does not substantially match an existing charge station in said charge station database.
12. The method of claim 7, wherein said location signals are GPS signals.
13. A non-transitory computer readable medium comprising computer executable code which when executed by a computer performs the steps of:
coupling a vehicle to a charge station;
determining a charge station location based upon a location of the vehicle when said connector is coupled to said charge station; and
transmitting, by said vehicle, said charge station location to a remote charge station database.
14. The non-transitory computer readable medium of claim 13, wherein said step of determining the charge station location further comprises the steps of:
receiving location signals; and
determining a change in location of said vehicle based upon movement occurring after said location signals are no longer received, and determining a charge station location by determining the location of the vehicle when the connector is coupled to the charge station based upon said location signals and said change in location determination.
15. The non-transitory computer readable medium of claim 14, wherein the step of determining a change in location includes the steps of:
measuring the distance traveled using wheel rotation measurements and
measuring changes in direction and elevation using gyroscope measurements.
16. The non-transitory computer readable medium of claim 13, further comprising the steps of:
determining charge station characteristics including at least one of charging rate or connection type; and
transmitting said charge station characteristics to the remote charge station database.
17. The non-transitory computer readable medium of claim 13, further comprising the steps of:
receiving said charge station information at a remote server, and
updating said charge station database with information about a new charge station when said received charge station location does not substantially match an existing charge station in said charge station database.
18. The non-transitory computer readable medium of claim 13, wherein said location signals are GPS signals.

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